CSc 360 Operating Systems Process Synchronization

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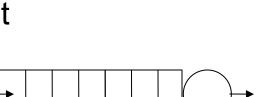
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The need for synchronization

- Multiprogramming
 - multi-process
 - process communication
 - shared memory or message passing
 - multi-thread
- CPU scheduling
- Cooperating processes/threads
 - e.g., the "producer-consumer" problem
 - cannot consume the things not produced yet

The producer-consumer problem

- Solutions so far
 - bounded buffer
 - in, out variables; full, empty conditions
 - N buffer space, N-1 utilized at most
 - first-in-first-out queue
 - FIFO variable
- A simpler solution
 - to fully utilize the circular buffer
 - use a "counter" variable



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The "counter" solution

```
while (true) {
   /* produce an item and put in nextProduced */
   while (count == BUFFER SIZE); // do nothing
   buffer [in] = nextProduced;
   in = (in + 1) % BUFFER SIZE;
                                             Producer
   count++;
while (true) {
   while (count == 0); // do nothing
   nextConsumed = buffer[out];
                                             Consumer
   out = (out + 1) % BUFFER SIZE;
   count--;
   /* consume the item in nextConsumed */
```

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Q: what's the problem?

Race condition

- E.g., increment a counter (shared variable)
 - read the counter (from memory)
 - increment by one (at CPU)
 - write the counter
- How about two threads?
 - sharing only one counter e.g., counter=5 initially
 - non-deterministic result: R₁W₁R₂W₂; R₁R₂W₁W₂
- "There is something not to be (always) shared"

Critical section

- Critical section
 - code section accessing shared data
 - only one thread executing in critical section
 - only one thread accessing the shared data: serialize
 - choose the right (size of) critical section!
- Approach: exclusion (lock)
 - if locked, wait!
 - if not lock, lock (and later, unlock)

Properties of "solutions"

- Mutual exclusion
 - no more than one process in the critical section
- Making progress
 - if no process in the critical section, one can in
- Bounded waiting
 - for processes that want to get in the critical section, their waiting time is bounded

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Problem formulation

- Only 2 processes, P₀ and P₁
- General structure of process P_i (other process P_j)
 do {

```
entry section
/* critical section */
exit section
/* remainder section */
} while (1);
```

- Processes may <u>share</u> some common variables to synchronize their actions
 - do not get into the loop!

Algorithm 1

Shared variables

```
int turn; // initially turn = 0
    - turn == i: P_i can enter its critical section

    Process P<sub>i</sub>

        do {
                 while (turn != i) ; // wait
                          /* critical section */
                 turn = j;
                          /* remainder section */
         } while (1);
```

Fate on other's hands: any problems?

Algorithm 2

Shared variables

```
boolean flag[2];
        initially flag [0] = flag [1] = false.
    - flag [i] = true : P_i ready to enter its critical section

    Process P<sub>i</sub>

          do {
                   flag[i] := true;
                   while (flag[j]); // wait
                             /* critical section */
                   flag [i] = false;
                             /* remainder section */
          } while (1);
```

Fight for access: any problems?



Dekker's solution

- Combined shared variables of Algorithms 1 and 2
- Process Pi

```
while (true) {
  flag[i] = true;
  while (flag[j]) {
    if (turn == j) {
      flag[i] = false;
      while (turn == j); // wait
      flag[i] = true;
    }
    /* critical section */
  turn = j;
  flag[i] = false;
    /* remainder section */
```

• Be polite! meet all three requirements; solve the critical-section problem for *two* processes

Peterson's solution

- A simpler solution
 - combined shared variables of Algorithms 1 and 2

 Meet all three requirements; solve the criticalsection problem for two processes

This lecture

- Process synchronization
 - the producer-consumer problem
 - software solution for 2 processes
 - Peterson's solution
- Explore further
 - Lamport's bakery algorithm
 - for *n* processes
 - it's time to google!

Next lecture

- Process synchronization
 - other alternatives (read OSC7Ch6)