

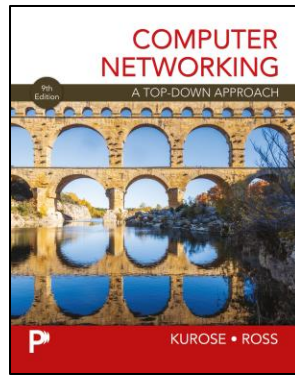
CSC 361

Computer Networks

Network Layer

(Chapter 5 – Control Plane)

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Summer 2026



Network Layer: “Control Plane” Roadmap (1 of 10)

- introduction
- routing protocols
 - link state
 - distance vector
- intra-ISP routing: OSPF
- routing among ISPs: BGP
- Internet Control Message Protocol

Network-Layer Functions

- **forwarding**: move packets from router's input to appropriate router output

data plane

- **routing**: determine route taken by packets from source to destination

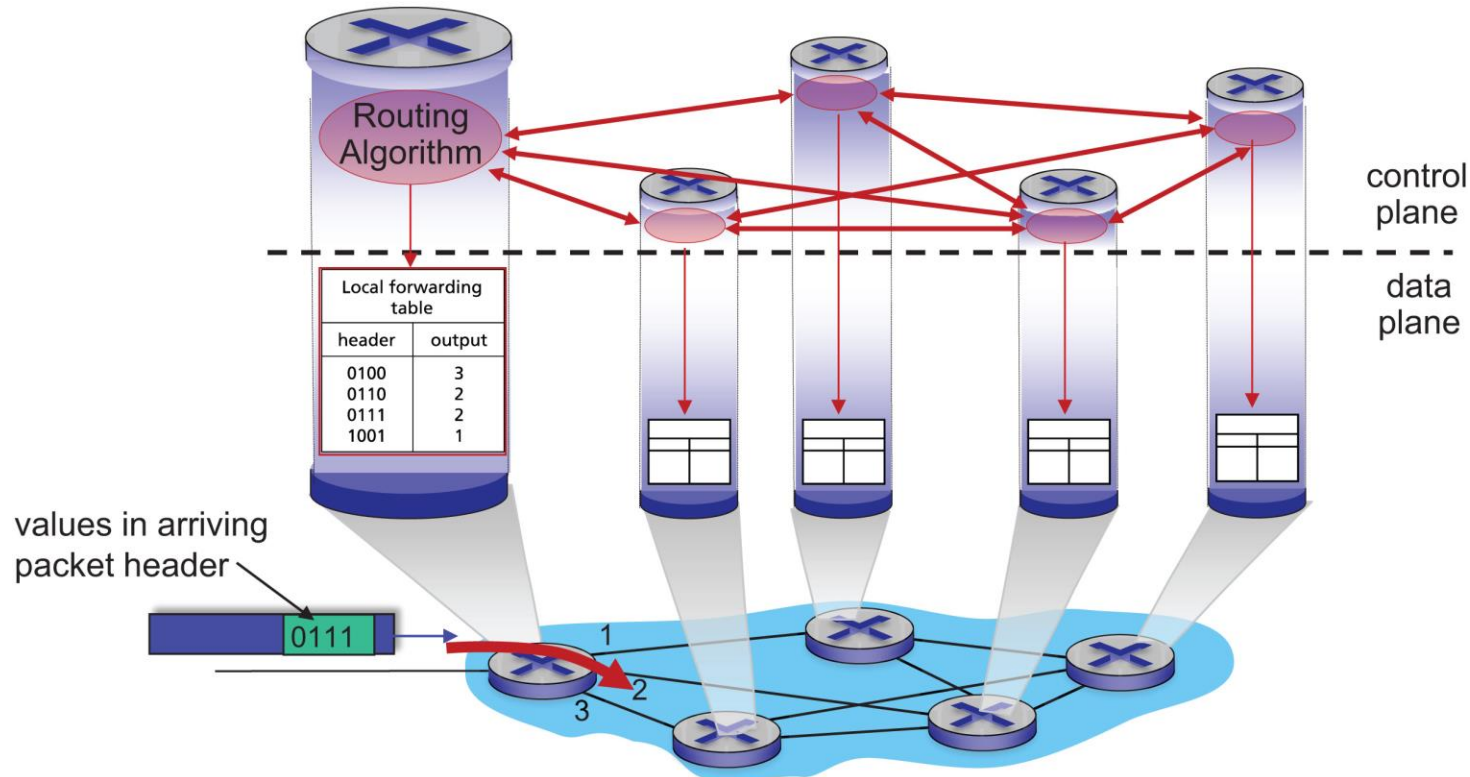
control plane

Two approaches to structuring network control plane:

- per-router control (traditional)
- logically centralized control (software defined networking)

Per-router Control Plane (1 of 2)

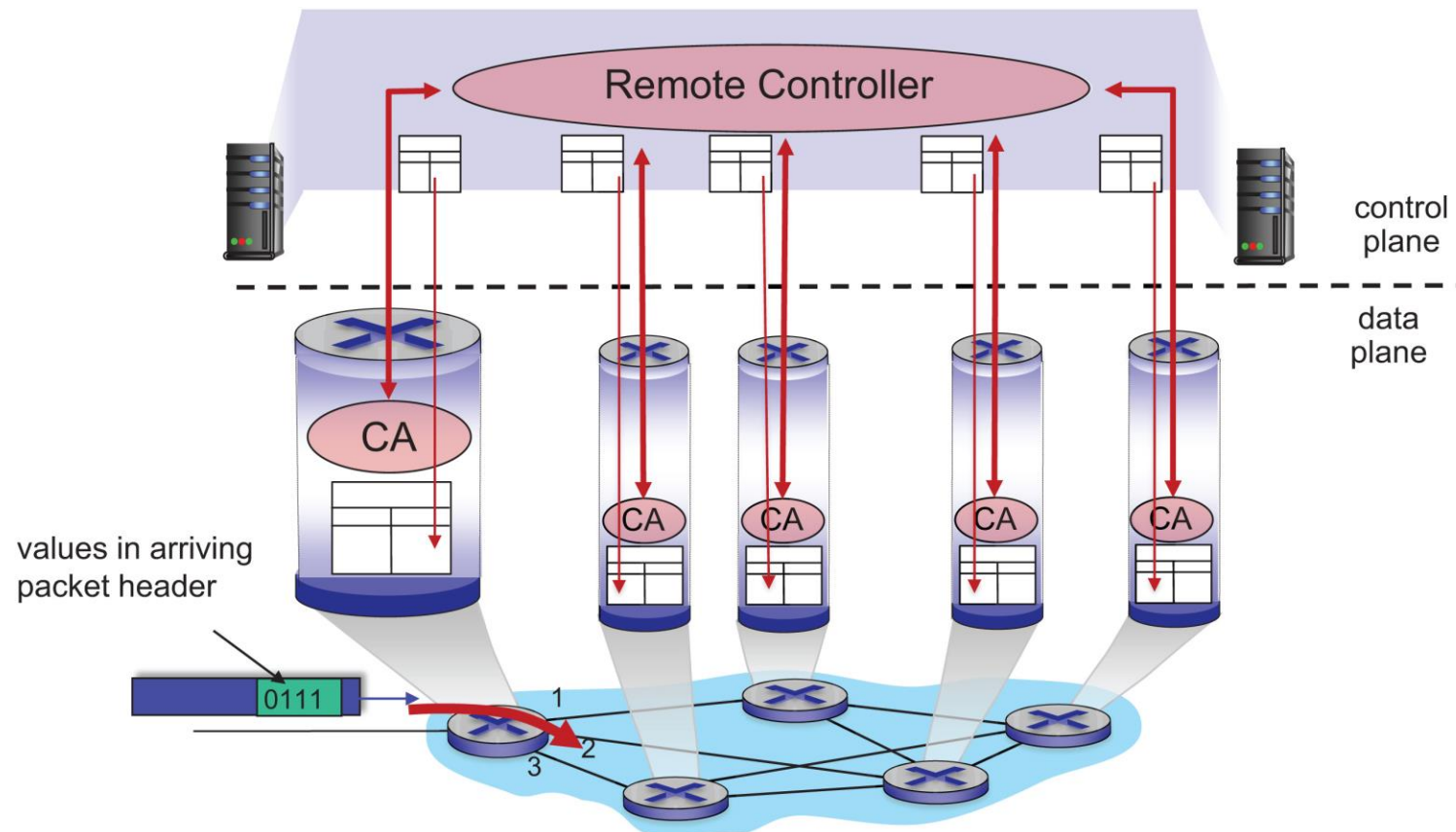
Individual routing algorithm components **in each and every router** interact in the control plane



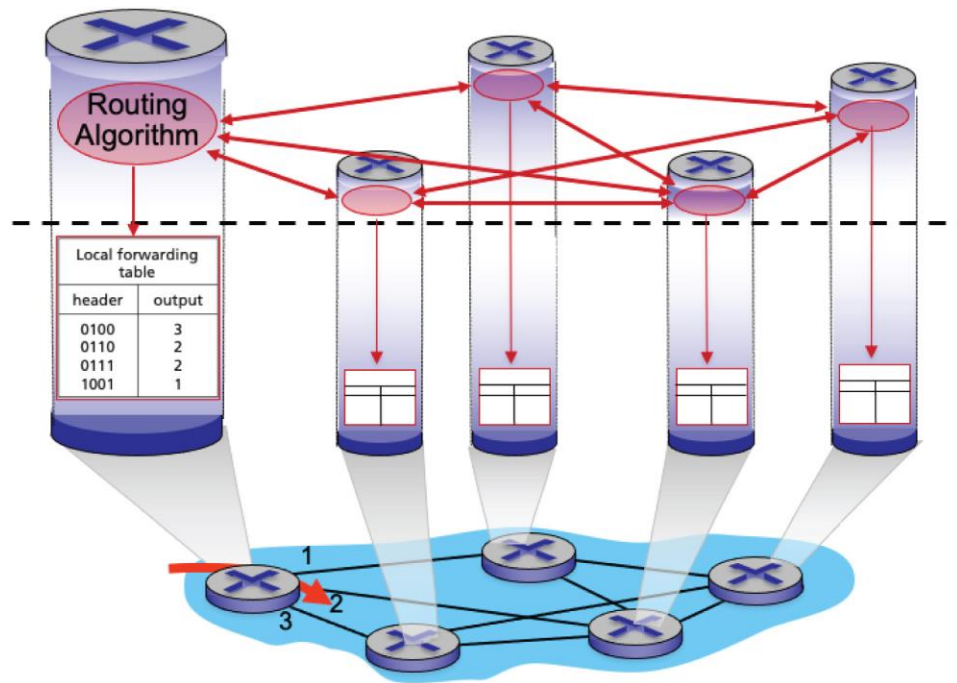
Software-Defined Networking (SDN) Control Plane

(1 of 2)

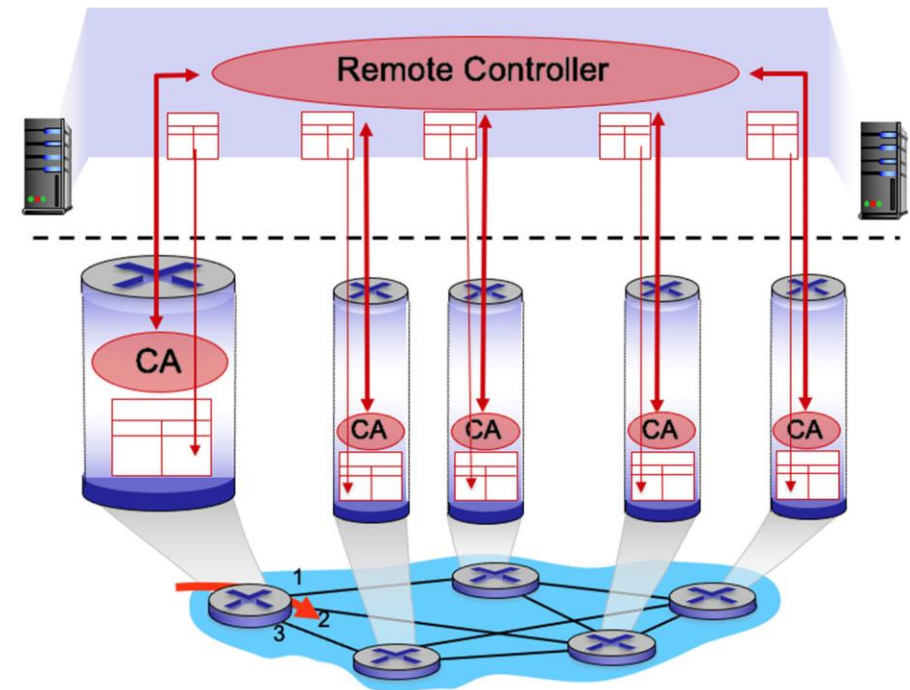
Remote controller computes, installs forwarding tables in routers



Per-router control plane



SDN control plane



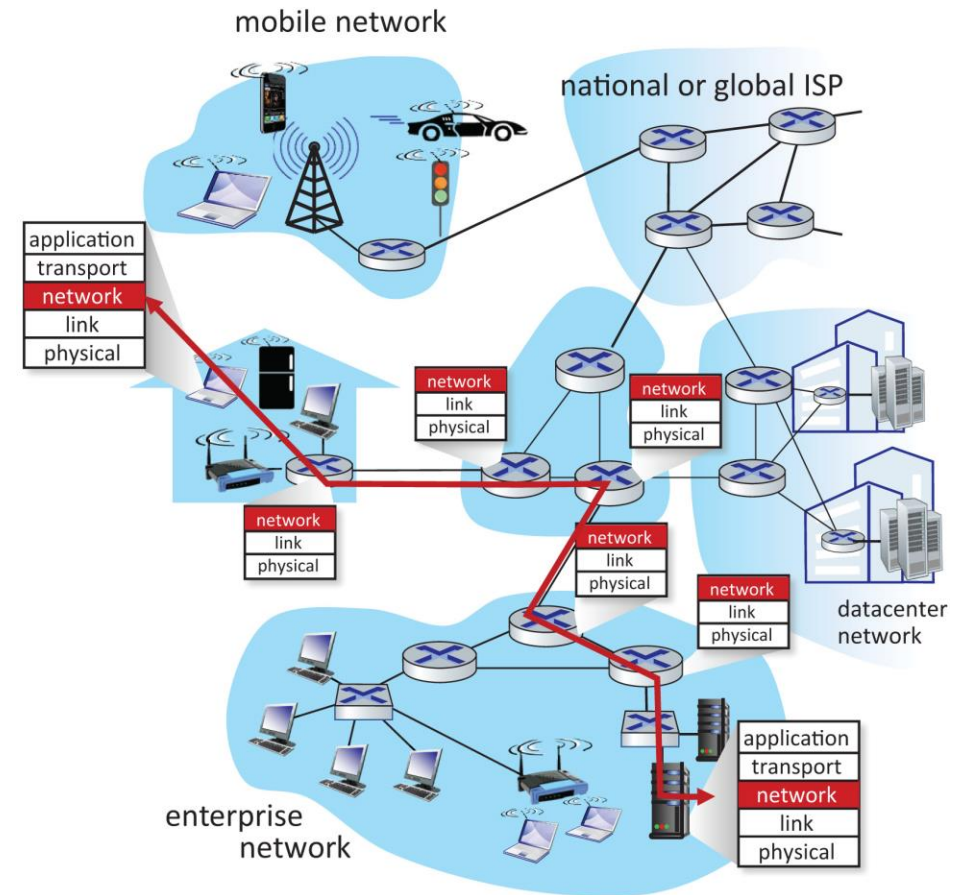
Network Layer: “Control Plane” Roadmap (2 of 10)

- introduction
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 - distance vector
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- Internet Control Message Protocol

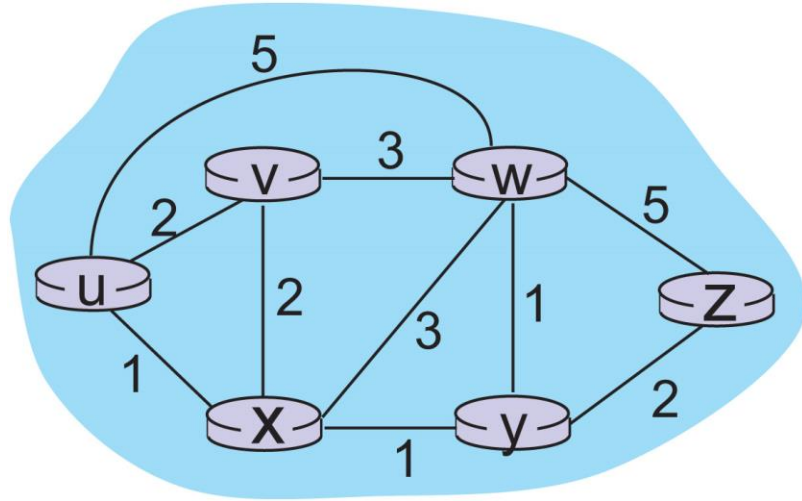
Routing Protocols

Routing protocol goal: determine “good” paths (equivalently, routes), from sending hosts to receiving host, through network of routers

- **path:** sequence of routers packets traverse from given initial source host to final destination host
- **“good”:** least “cost”, “fastest”, “least congested”
- routing: a “top-10” networking challenge!



Graph Abstraction: Link Costs



$c_{a,b}$: cost of **direct** link connecting a and b

e.g., $c_{w,z} = 5, c_{u,z} = \infty$

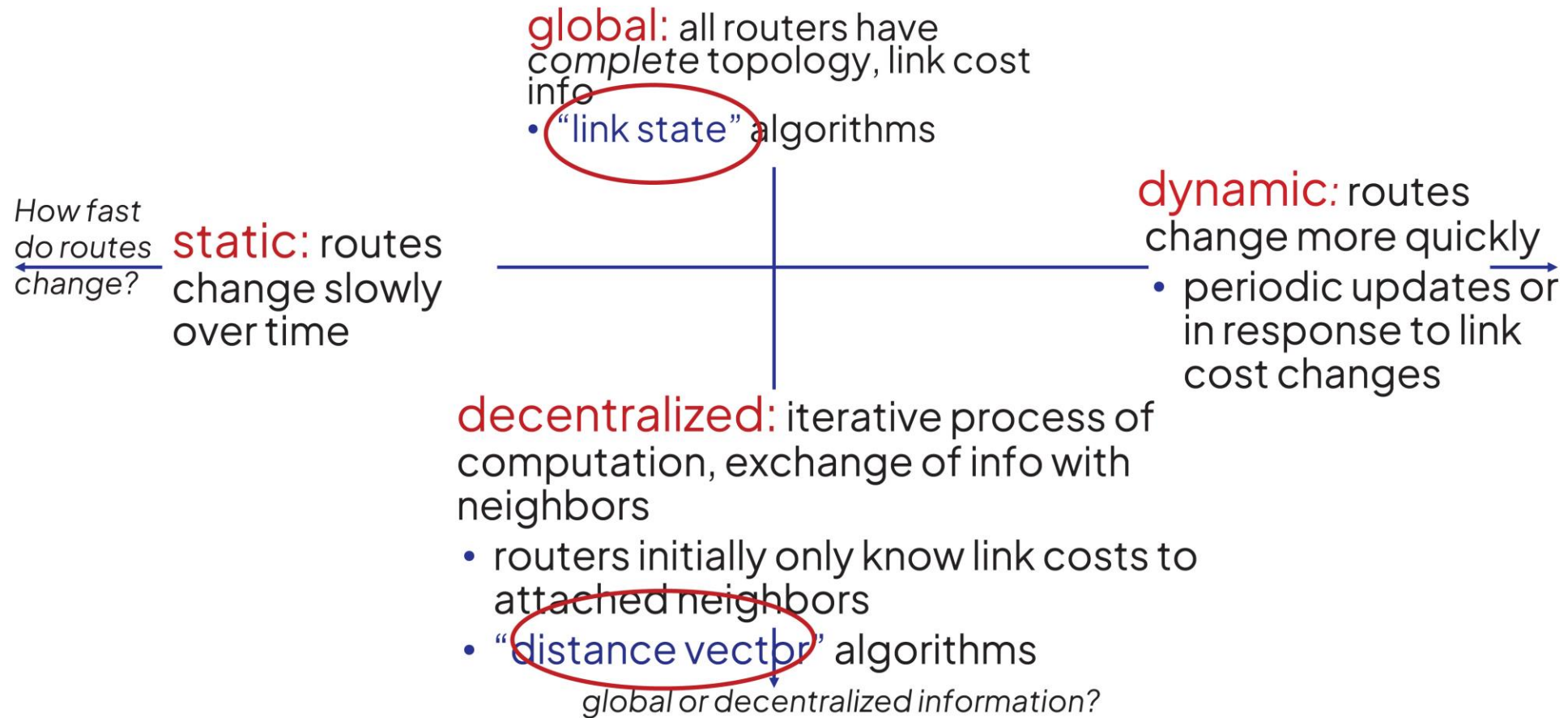
cost defined by network operator:
could always be 1, or inversely related
to bandwidth, or inversely related to
congestion

graph: $G = (N, E)$

N : set of routers $= \{u, v, w, x, y, z\}$

E : set of links $= \{ (u, v), (u, x), (v, x), (v, w), (x, w), (x, y), (w, y), (w, z), (y, z) \}$

Routing Algorithm Classification



Network Layer: “Control Plane” Roadmap (3 of 10)

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Dijkstra's Link-State Routing Algorithm (1 of 2)

- **centralized**: network topology, link costs known to **all** nodes
 - accomplished via “link state broadcast”
 - all nodes have same info
- computes least cost paths from one node (“source”) to all other nodes
 - gives **forwarding table** for that node
- **iterative**: after k iterations, know least cost path to k destinations

notation

- $c_{x,y}$: **direct** link cost from node x to y ; $= \infty$ if not direct neighbors
- $D(v)$: **current** estimate of cost of least-cost-path from source to destination v
- $p(v)$: predecessor node along path from source to v
- N' : set of nodes whose least-cost-path **definitively** known

Dijkstra's Link-State Routing Algorithm (2 of 2)

1 *Initialization:*

2 $N' = \{u\}$ */* compute least cost path from u to all other nodes */*

3 for all nodes v

4 if v adjacent to u */* u initially knows direct-path-cost only to direct neighbors */*

5 then $D(v) = c_{u,v}$ */* but may not be minimum cost! */*

6 else $D(v) = \infty$

7

8 *Loop*

9 find w not in N' such that $D(w)$ is a minimum

10 add w to N'

11. update $D(v)$ for all v adjacent to w and not in N' :

12 **$D(v) = \min (D(v), D(w) + c_{w,v})$**

13 */* new least-path-cost to v is either old least-cost-path to v or known*

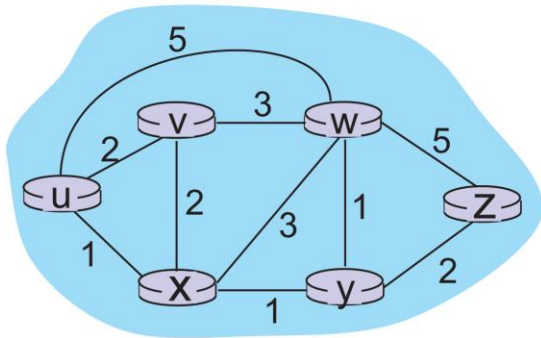
14 *least-cost-path to w plus direct-cost from w to v */*

15 *until all nodes in N'*

Dijkstra's Algorithm: An Example (1 of 13)

Step	N'	^v D(v),p (v)	^w D(w),p (w)	^x D(x),p (x)	^y D(y),p (y)	^z D(z),p (z)
0	u	2,u	5,u	1,u	∞	∞
1						
2						
3						
4						
5						

D(w),p (w)
5,u
4,x
3,y
3,y



Initialization (step 0):

For all *a*: if *a* adjacent to *u* then $D(a)=c_{u,a}$

Dijkstra's Algorithm: An Example (2 of 13)

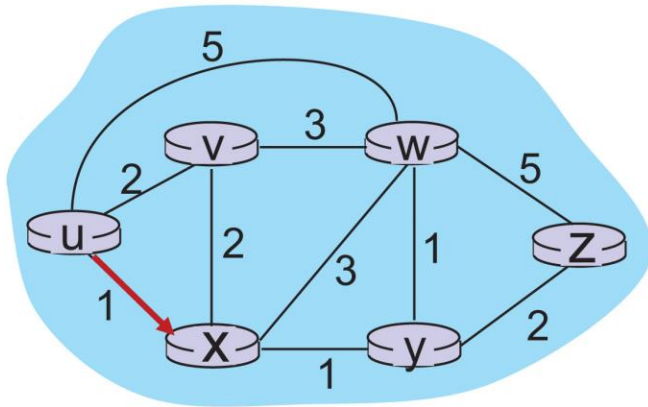
Step	N'	$D(v), p(v)$	$D(w), p(w)$	$D(x), p(x)$	$D(y), p(y)$	$D(z), p(z)$
0	u	2, u	5, u	1, u	∞	∞
1	u, x					
2						
3						
4						
5						

$D(w), p(w)$
 5, u
 4, x
 3, y
 3, y

8 Loop

9 find a not in N' such that $D(a)$ is a minimum

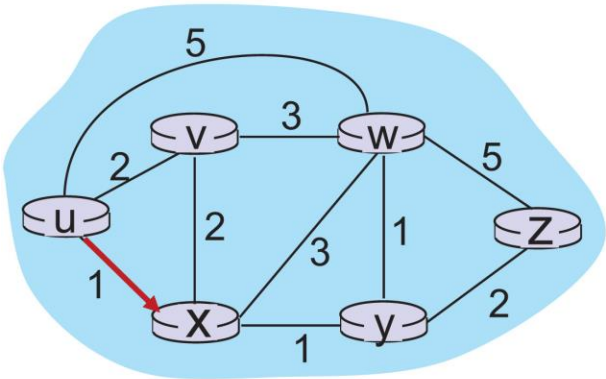
10 add a to N'



Dijkstra's Algorithm: An Example (3 of 13)

Step	N'	V D(v),p(v)	W D(w),p(w)	X D(x),p(x)	Y D(y),p(y)	Z D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2						
3						
4						
5						

D(w),p(w)
5,u
4,x
3,y
3,y



8 Loop

- 9 find a not in N' such that $D(a)$ is a minimum
- 10 add a to N'
- 11 update $D(b)$ for all b adjacent to a and not in N' :

$$D(b) = \min (D(b), D(a) + c_{a,b})$$

$$D(v) = \min (D(v), D(x) + c_{x,v}) = \min (2, 1+2) = 2$$

$$D(w) = \min (D(w), D(x) + c_{x,w}) = \min (5, 1+3) = 4$$

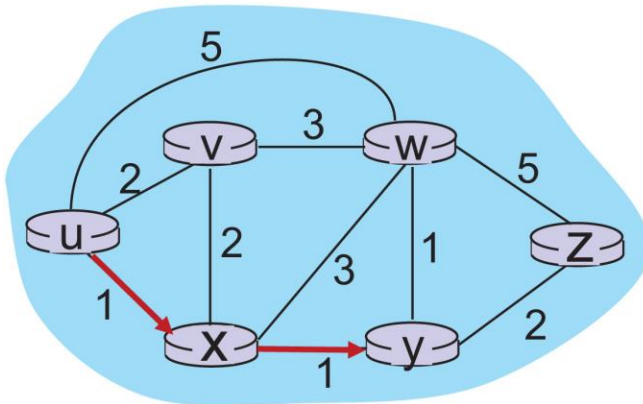
$$D(y) = \min (D(y), D(x) + c_{x,y}) = \min (\infty, 1+1) = 2$$



Dijkstra's Algorithm: An Example (4 of 13)

Step	N'	$D(v), p(v)$	$D(w), p(w)$	$D(x), p(x)$	$D(y), p(y)$	$D(z), p(z)$
0	u	2, u	5, u	1, u	∞	∞
1	ux	2, u	4, x		2, x	∞
2	uxy					
3						
4						
5						

$D(w), p(w)$
 5, u
 4, x
 3, y
 3, y

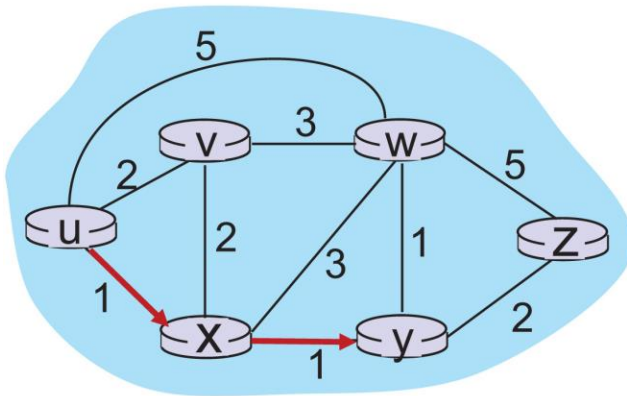


8 Loop

9 find a not in N' such that $D(a)$ is a
 10 minimum
 add a to N'

Dijkstra's Algorithm: An Example (5 of 13)

		v	w	x	y	z
Step	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3						
4						
5						



8 Loop

9 find a not in N' such that $D(a)$ is a minimum

10 add a to N'

11 update $D(b)$ for all b adjacent to a and not in N' :

$$D(b) = \min (D(b), D(a) + c_{a,b})$$

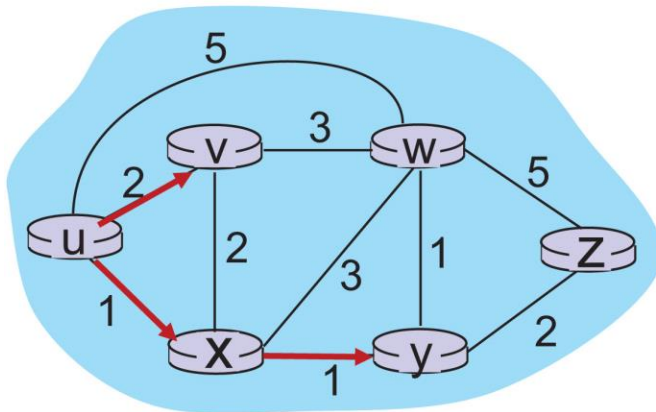
$$D(w) = \min (D(w), D(y) + c_{y,w}) = \min (4, 2+1) = 3$$

$$D(z) = \min (D(z), D(y) + c_{y,z}) = \min (\infty, 2+2) = 4$$



Dijkstra's Algorithm: An Example (6 of 13)

Step	N'	$D(v), p(v)$	$D(w), p(w)$	$D(x), p(x)$	$D(y), p(y)$	$D(z), p(z)$
0	u	2, u	5, u	1, u	∞	∞
1	ux	2, u	4, x		2, x	∞
2	uxy	2, u	3, y			4, y
3	uxyv					
4						
5						



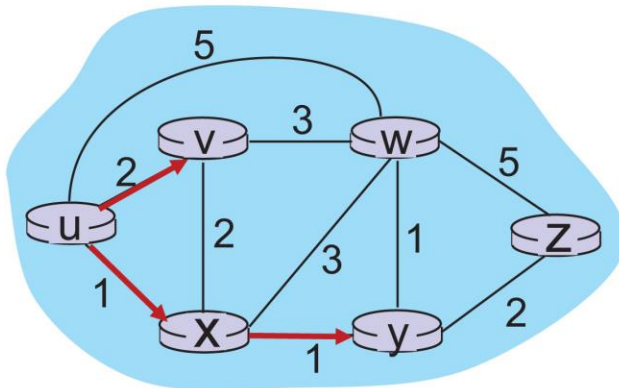
8 Loop

9 find a not in N' such that $D(a)$ is a minimum

10 add a to N'

Dijkstra's Algorithm: An Example (7 of 13)

Step	N'	v D(v),p(v)	w D(w),p(w)	x D(x),p(x)	y D(y),p(y)	z D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4						
5						



8 Loop

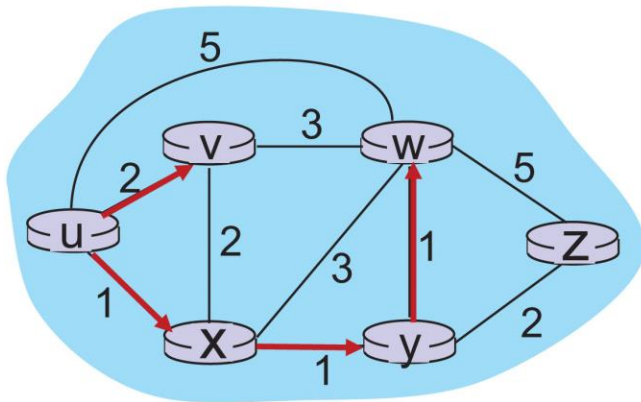
- 9 find a not in N' such that $D(a)$ is a minimum
- 10 add a to N'
- 11 update $D(b)$ for all b adjacent to a and not in N' :

$$D(b) = \min (D(b), D(a) + c_{a,b})$$

$$D(w) = \min (D(w), D(v) + c_{v,w}) = \min (3, 2+3) = 3$$

Dijkstra's Algorithm: An Example (8 of 13)

Step	N'	$D(v), p(v)$	$D(w), p(w)$	$D(x), p(x)$	$D(y), p(y)$	$D(z), p(z)$
0	u	2, u	5, u	1, u	∞	∞
1	ux	2, u	4, x	2, x	∞	∞
2	uxy	2, u	3, y	4, y	∞	∞
3	uxyv	2, u	3, y	4, y	∞	∞
4	uxyvw	2, u	3, y	4, y	∞	∞
5						



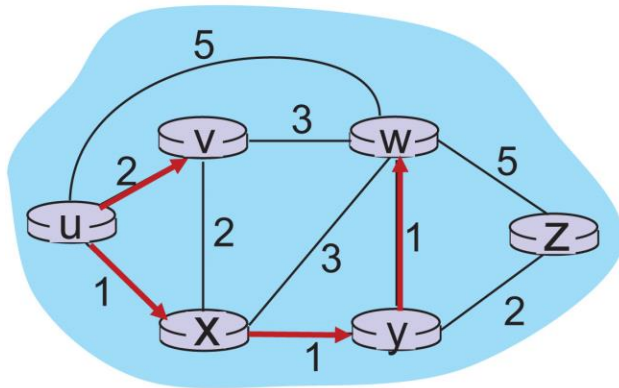
8 Loop

9 find a not in N' such that $D(a)$ is a minimum

10 add a to N'

Dijkstra's Algorithm: An Example (9 of 13)

Step	N'	v D(v),p(v)	w D(w),p(w)	x D(x),p(x)	y D(y),p(y)	z D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw					4,y
5						



8 Loop

9 find a not in N' such that $D(a)$ is a minimum

10 add a to N'

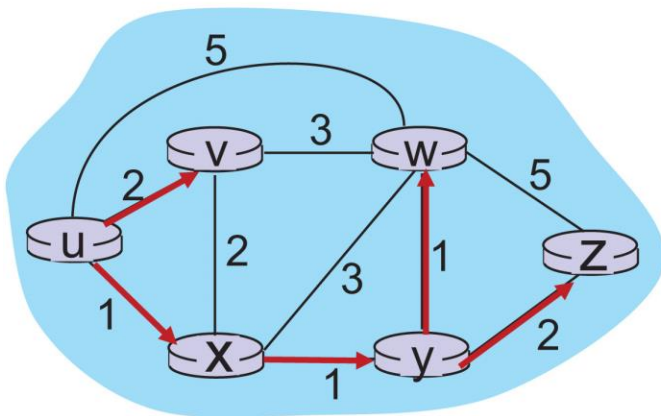
11 update $D(b)$ for all b adjacent to a and not in N' :

$$D(b) = \min (D(b), D(a) + c_{a,b})$$

$$D(z) = \min (D(z), D(w) + c_{w,z}) = \min (4, 3+5) = 4$$

Dijkstra's Algorithm: An Example (10 of 13)

Step	N'	$D(v), p(v)$	$D(w), p(w)$	$D(x), p(x)$	$D(y), p(y)$	$D(z), p(z)$
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw					4,y
5	uxyvwz					

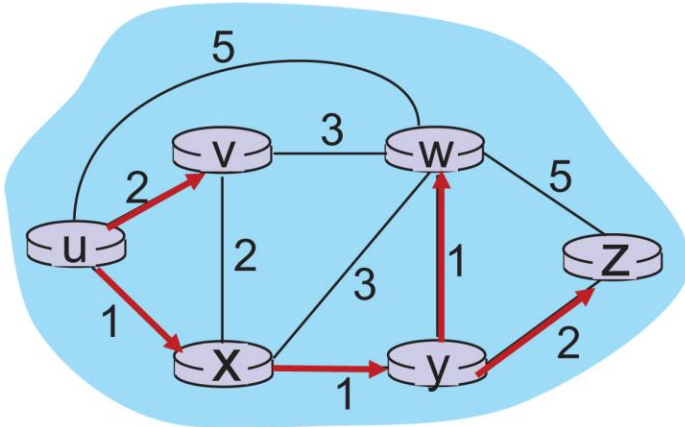


8 Loop

- 9 find a not in N' such that $D(a)$ is a minimum
- 10 add a to N'

Dijkstra's Algorithm: An Example (11 of 13)

		V	W	X	Y	Z
Step	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw					4,y
5	uxyvwz					



8 Loop

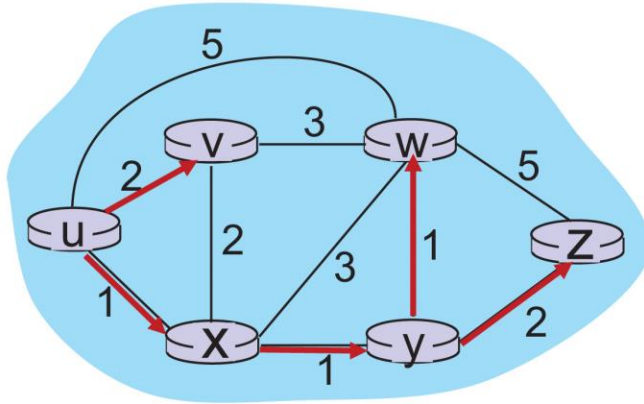
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- 10 add a to N'
- 11 update $D(b)$ for all b adjacent to a and not in N' :

$$D(b) = \min (D(b), D(a) + c_{a,b})$$

Dijkstra's Algorithm: An Example (12 of 13)

Step	N'	$D(v), p(v)$	$D(w), p(w)$	$D(x), p(x)$	$D(y), p(y)$	$D(z), p(z)$
0	u	2, u	5, u	1, u	∞	∞
1	ux	2, u	4, x	2, x	∞	∞
2	uxy	2, u	3, y	4, y	4, y	∞
3	uxyv	2, u	3, y	4, y	4, y	∞
4	uxyvw	2, u	3, y	4, y	4, y	∞
5	uxyvwz	2, u	3, y	4, y	4, y	∞

$D(w), p(w)$
 5, u
 4, x
 3, y
 3, y



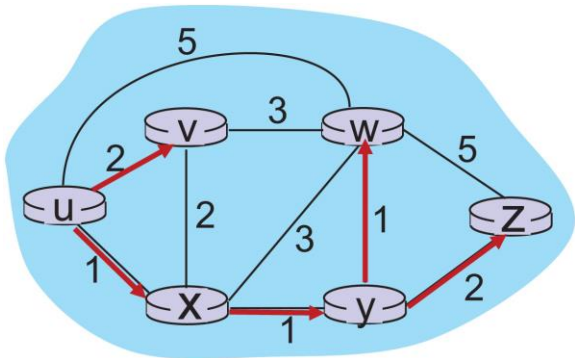
Initialization (step 0): For all a : if a adjacent to then $D(a) = c_{u,a}$

find a not in N' such that $D(a)$ is a minimum
 add a to N'

update $D(b)$ for all b adjacent to a and not in N' :

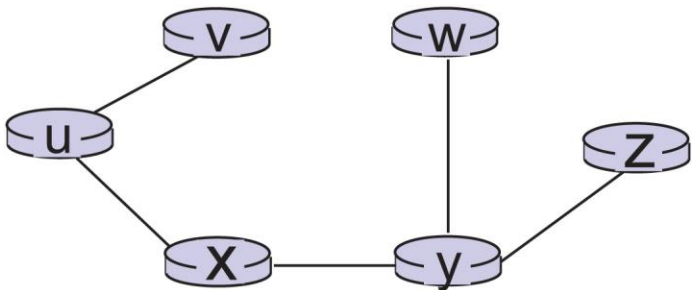
$$D(b) = \min (D(b), D(a) + c_{a,b})$$

Dijkstra's Algorithm: An Example (13 of 13)



D(w),p (w)
5,u
4,x
3,y
3,y

resulting least-cost-path tree from u:



resulting forwarding table in u:

destination	outgoing link
v	(u,v)
x	(u,x)
y	(u,x)
w	(u,x)
x	(u,x)

route from u to v directly

route from u to all other destinations via x

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- Internet Control Message Protocol

Distance Vector Algorithm (1 of 2)

Based on **Bellman-Ford** (BF) equation (dynamic programming):

Bellman-Ford equation

Let $D_x(y)$: cost of least-cost path from x to y .

Then:

$$D_x(y) = \min_v \{ c_{x,v} + D_v(y) \}$$

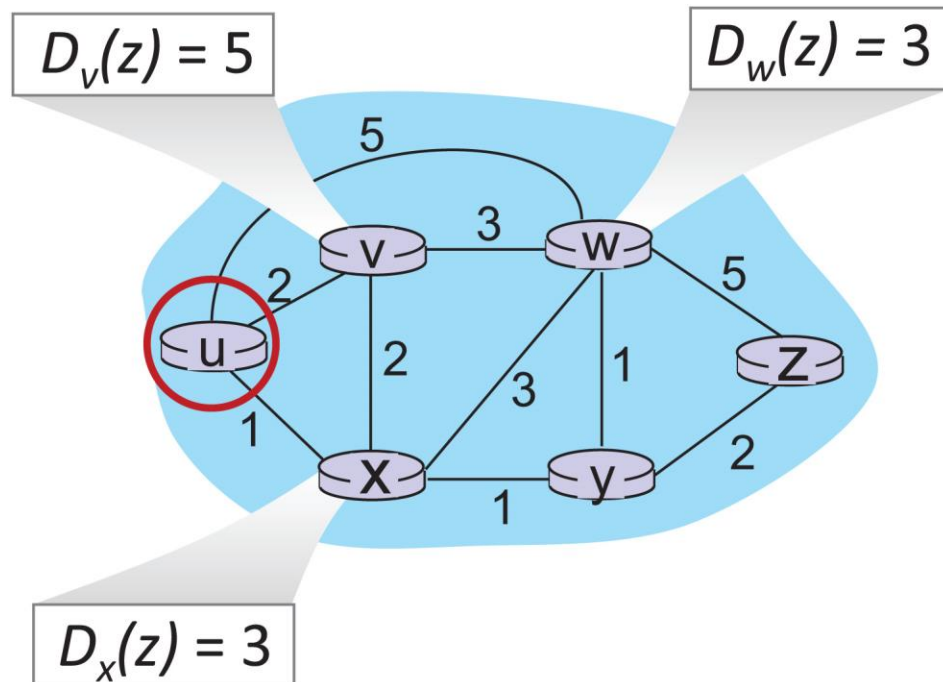
min taken over all
neighbors v of x

direct cost
of link
from x to v

v 's estimated least-cost-
path cost to y

Bellman-Ford Example

Suppose that u 's neighboring nodes, x, v, w , know that for destination z :



Bellman-Ford equation says:

$$D_u(z) = \min \{ c_{u,v} + D_v(z), \\ c_{u,x} + D_x(z), \\ c_{u,w} + D_w(z) \}$$

$$= \min \{ 2 + 5, 1 + 3, 5 + 3 \} = 4$$

node achieving minimum (x) is next hop on estimated least-cost path to destination (z)

Distance Vector Algorithm (2 of 2)

key idea:

- from time-to-time, each node sends its own distance vector estimate to neighbors
- when x receives new DV estimate from any neighbor, it updates its own DV using B-F equation:

$$D_x(y) \leftarrow \min_v \{c_{x,v} + D_v(y)\} \text{ for each node } y \in N$$

- under minor, natural conditions, the estimate $D_x(y)$ converge to the converge to the actual least cost $d_x(y)$

Distance Vector Algorithm:

each node:

wait for (change in local link cost or msg from neighbor)



recompute DV estimates using DV received from neighbor



if DV to any destination has changed, **notify** neighbors

iterative, asynchronous: each local iteration caused by:

- local link cost change
- DV update message from neighbor

distributed, self-stopping: each node notifies neighbors **only** when its DV changes

- neighbors then notify their neighbors – **only if necessary**
- no notification received, no actions taken!

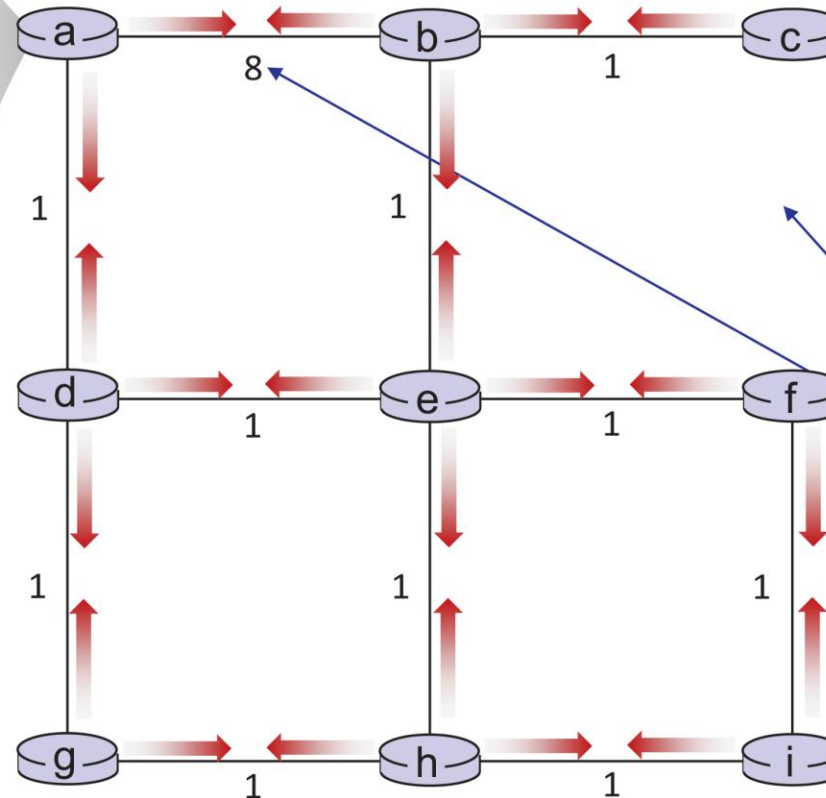
Distance Vector: Example



t=0

- All nodes have distance estimates to nearest neighbors (only)
- All nodes send their local distance vector to their neighbors

DV in a:	
$D_a(a)$	0
$D_a(b)$	8
$D_a(c)$	∞
$D_a(d)$	1
$D_a(e)$	∞
$D_a(f)$	∞
$D_a(g)$	∞
$D_a(h)$	∞
$D_a(i)$	∞



A few asymmetries:
■ missing link
■ larger cost

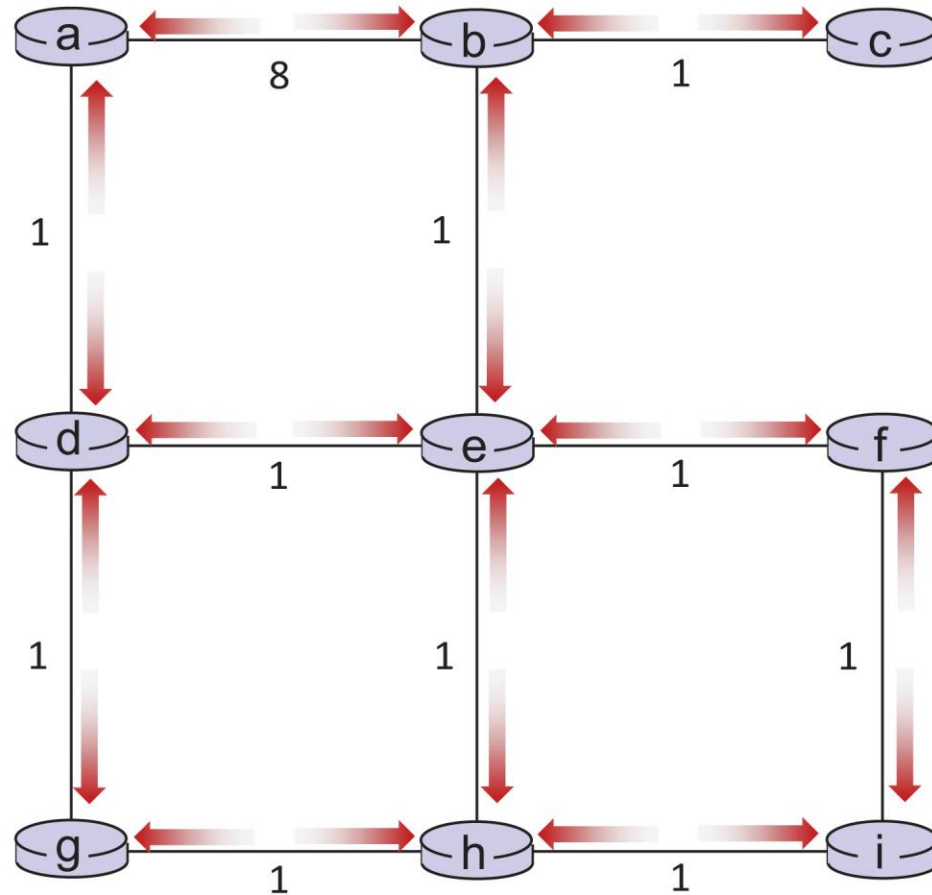
Distance Vector Example: Iteration (1 of 7)



$t=1$

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



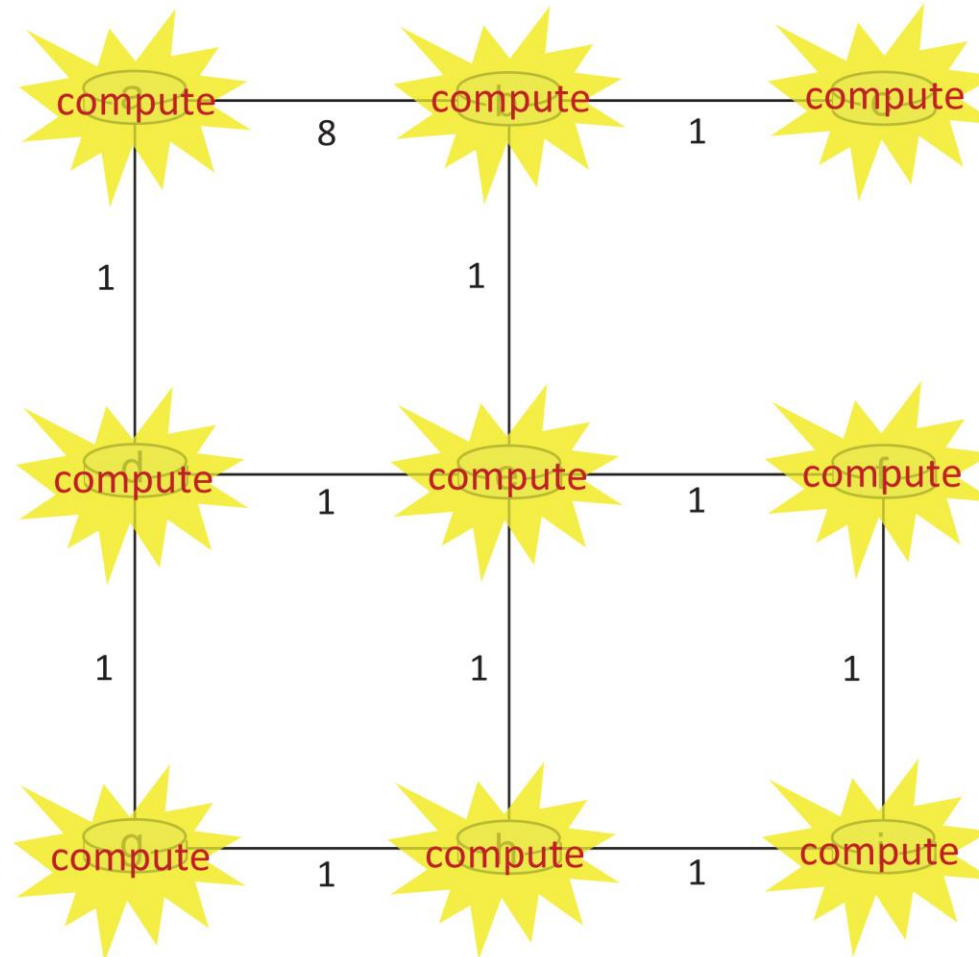
Distance Vector Example: Iteration (2 of 7)



t=1

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



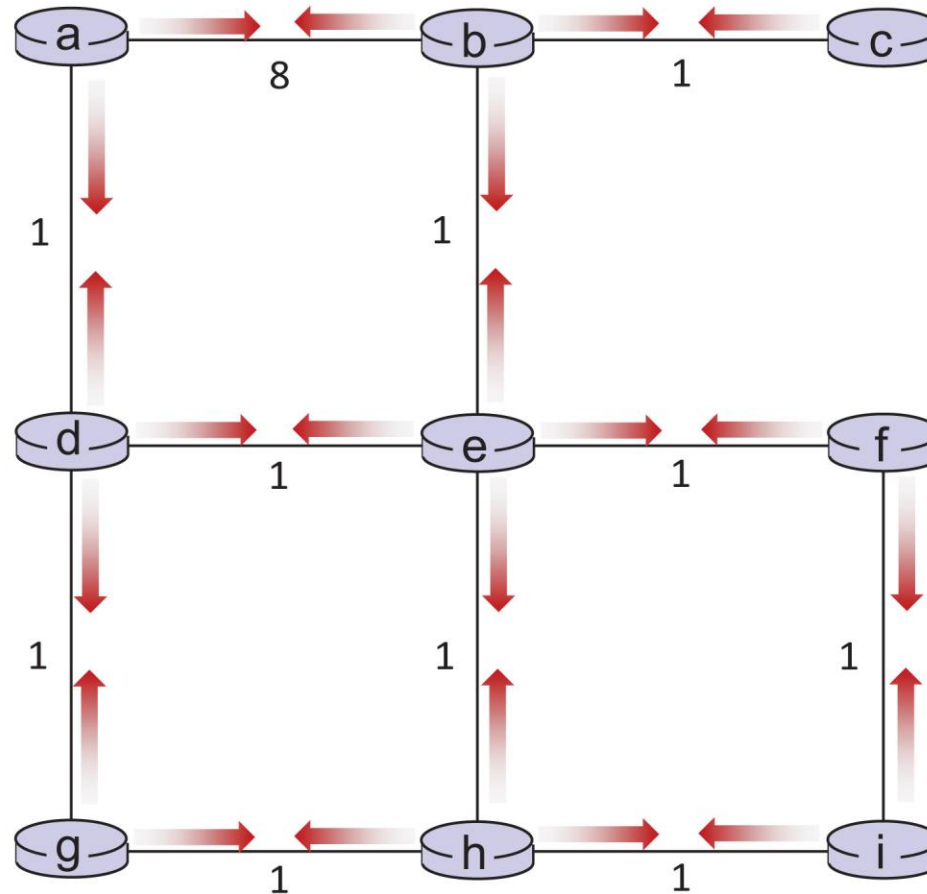
Distance Vector Example: Iteration (3 of 7)



$t=1$

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



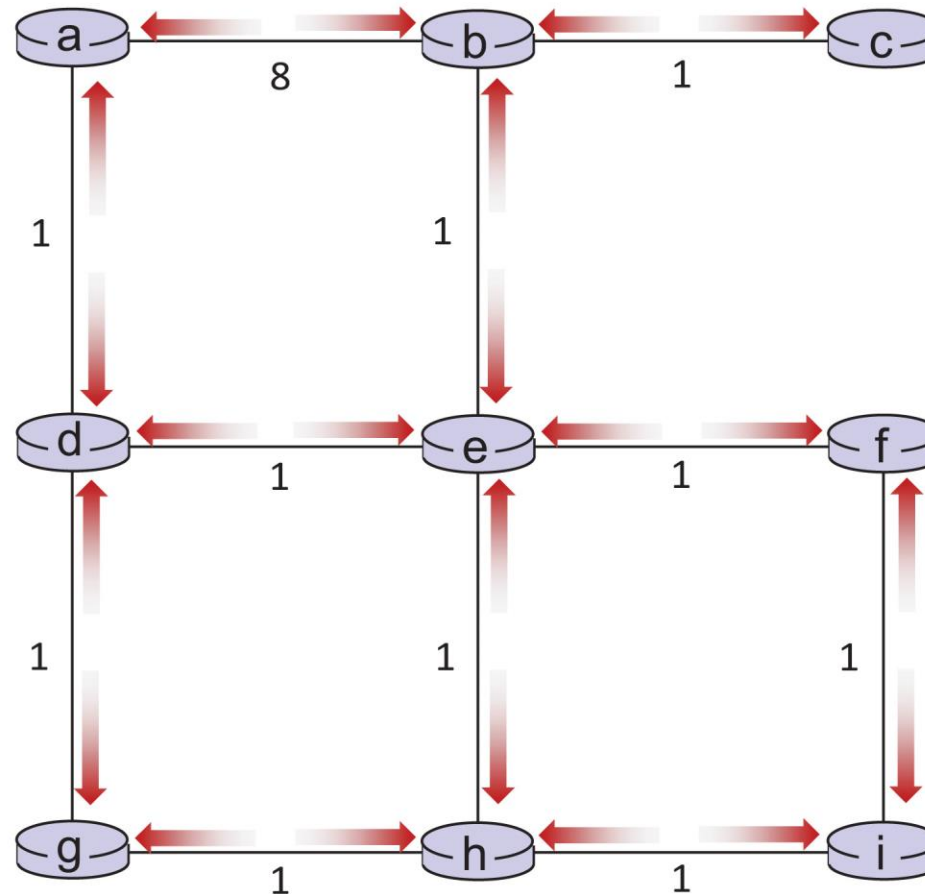
Distance Vector Example: Iteration (4 of 7)



t=2

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



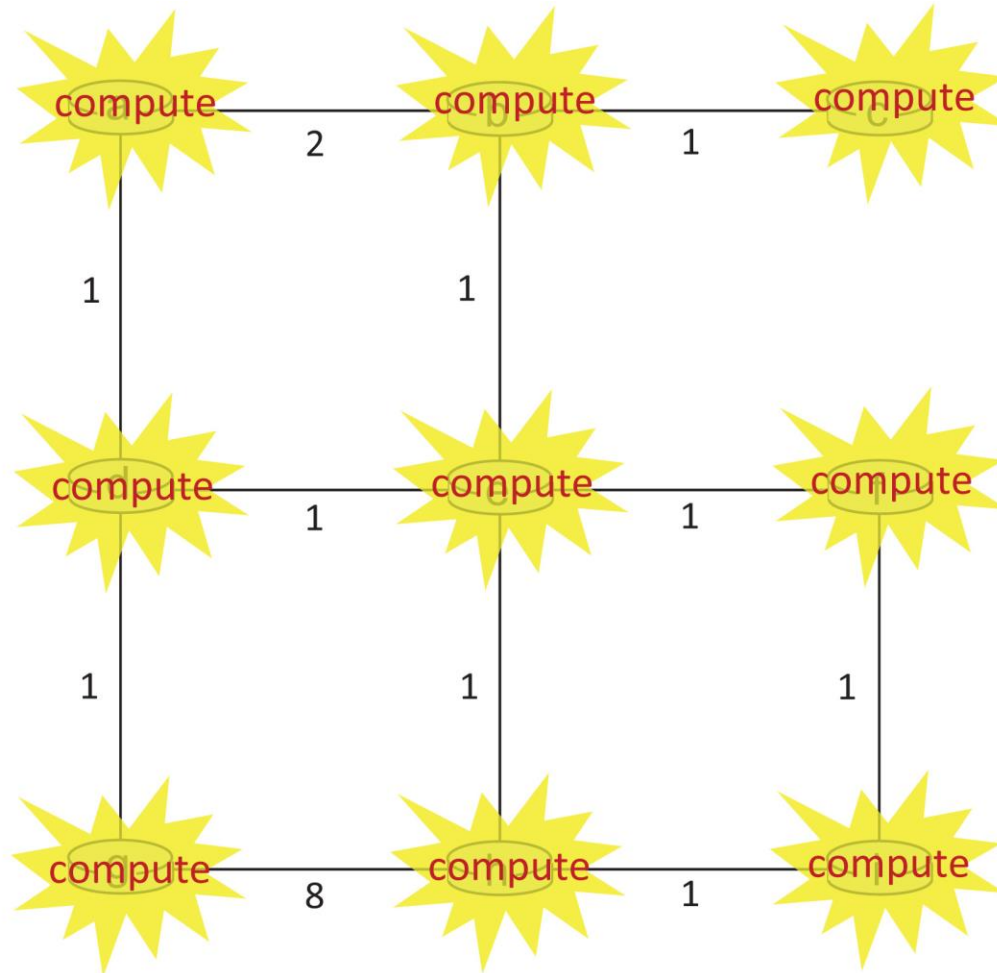
Distance Vector Example: Iteration (5 of 7)



t=2

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



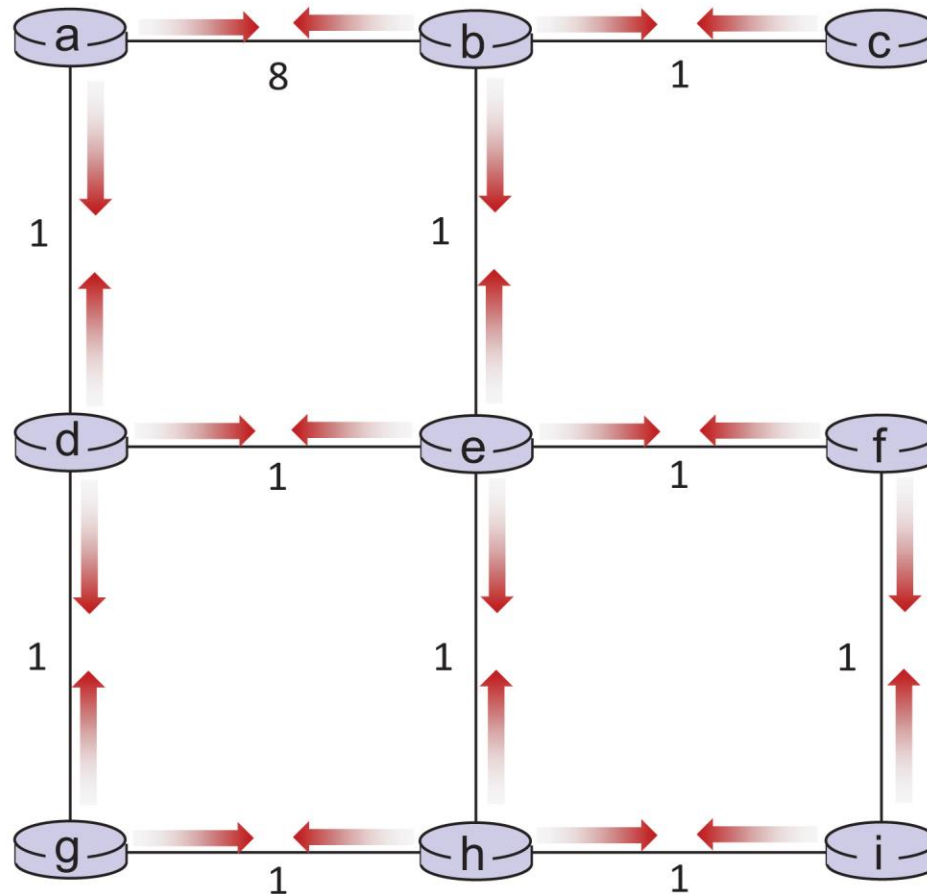
Distance Vector Example: Iteration (6 of 7)



t=2

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



Distance Vector Example: Iteration (7 of 7)

.... and so on

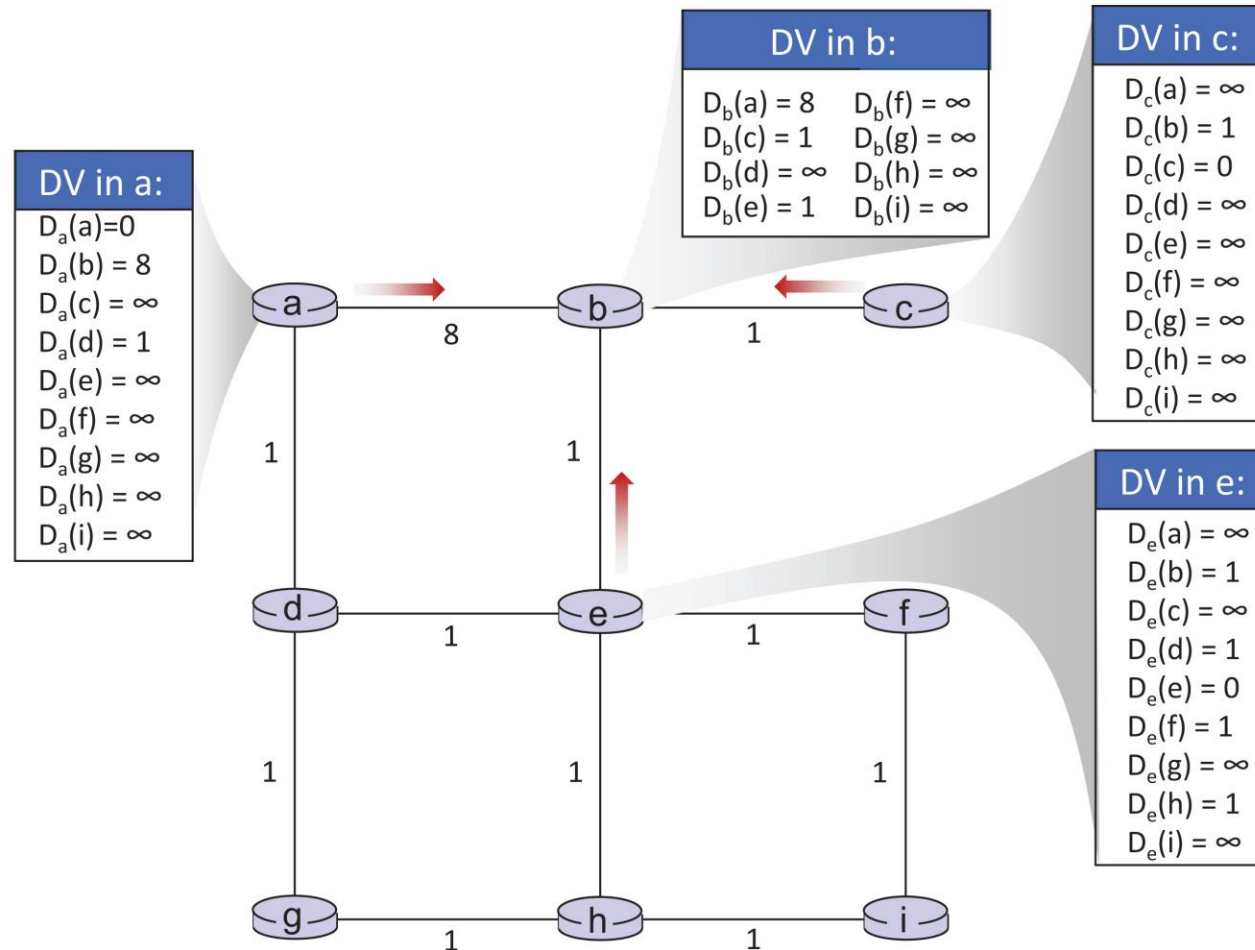
Let's next take a look at the iterative **computations** at nodes

Distance Vector Example: Computation (1 of 5)



t=1

- b receives DVs from a, c, e



Distance Vector Example: Computation (2 of 5)



t=1

- b receives DVs from a, c, e, computes:

$$\begin{aligned}
 D_b(a) &= \min\{c_{b,a} + D_a(a), c_{b,c} + D_c(a), c_{b,e} + D_e(a)\} = \min\{8, \infty, \infty\} = 8 \\
 D_b(c) &= \min\{c_{b,a} + D_a(c), c_{b,c} + D_c(c), c_{b,e} + D_e(c)\} = \min\{\infty, 1, \infty\} = 1 \\
 D_b(d) &= \min\{c_{b,a} + D_a(d), c_{b,c} + D_c(d), c_{b,e} + D_e(d)\} = \min\{9, 2, \infty\} = 2 \\
 D_b(e) &= \min\{c_{b,a} + D_a(e), c_{b,c} + D_c(e), c_{b,e} + D_e(e)\} = \min\{\infty, \infty, 1\} = 1 \\
 D_b(f) &= \min\{c_{b,a} + D_a(f), c_{b,c} + D_c(f), c_{b,e} + D_e(f)\} = \min\{\infty, \infty, 2\} = 2 \\
 D_b(g) &= \min\{c_{b,a} + D_a(g), c_{b,c} + D_c(g), c_{b,e} + D_e(g)\} = \min\{\infty, \infty, \infty\} = \infty \\
 D_b(h) &= \min\{c_{b,a} + D_a(h), c_{b,c} + D_c(h), c_{b,e} + D_e(h)\} = \min\{\infty, \infty, 2\} = 2 \\
 D_b(i) &= \min\{c_{b,a} + D_a(i), c_{b,c} + D_c(i), c_{b,e} + D_e(i)\} = \min\{\infty, \infty, \infty\} = \infty
 \end{aligned}$$

DV in a:
$D_a(a)=0$
$D_a(b)=8$
$D_a(c)=\infty$
$D_a(d)=1$
$D_a(e)=\infty$
$D_a(f)=\infty$
$D_a(g)=\infty$
$D_a(h)=\infty$
$D_a(i)=\infty$

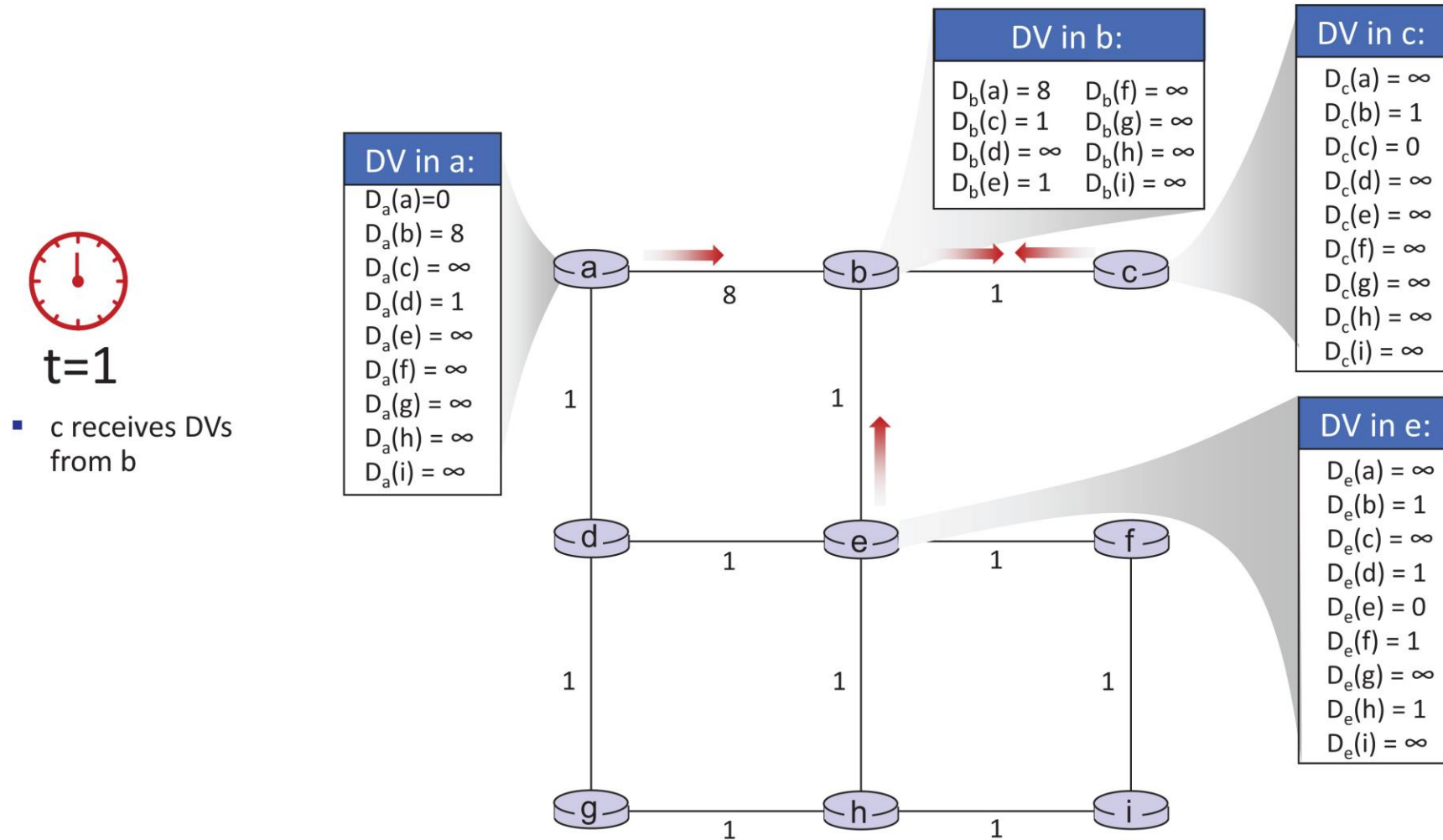
DV in b:	
$D_b(a)=8$	$D_b(f)=\infty$
$D_b(c)=1$	$D_b(g)=\infty$
$D_b(d)=\infty$	$D_b(h)=\infty$
$D_b(e)=1$	$D_b(i)=\infty$

DV in c:
$D_c(a)=\infty$
$D_c(b)=1$
$D_c(c)=0$
$D_c(d)=\infty$
$D_c(e)=\infty$
$D_c(f)=\infty$
$D_c(g)=\infty$
$D_c(h)=\infty$
$D_c(i)=\infty$

DV in e:
$D_e(a)=\infty$
$D_e(b)=1$
$D_e(c)=\infty$
$D_e(d)=1$
$D_e(e)=0$
$D_e(f)=1$
$D_e(g)=\infty$
$D_e(h)=1$
$D_e(i)=\infty$

DV in b:	
$D_b(a)=8$	$D_b(f)=2$
$D_b(c)=1$	$D_b(g)=\infty$
$D_b(d)=2$	$D_b(h)=2$
$D_b(e)=1$	$D_b(i)=\infty$

Distance Vector Example: Computation (3 of 5)



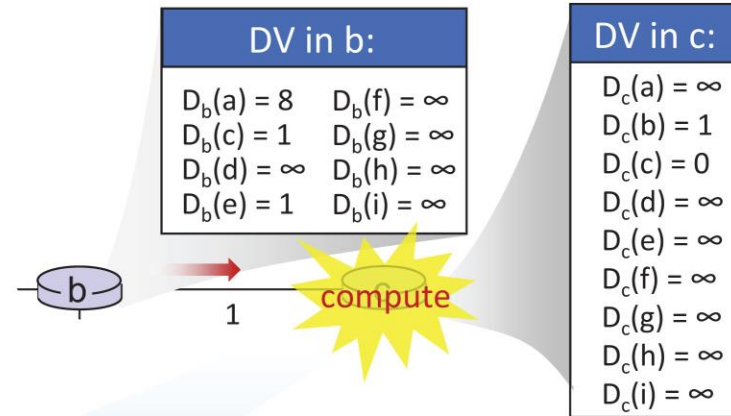
Distance Vector Example: Computation (4 of 5)



t=1

- c receives DVs from b computes:

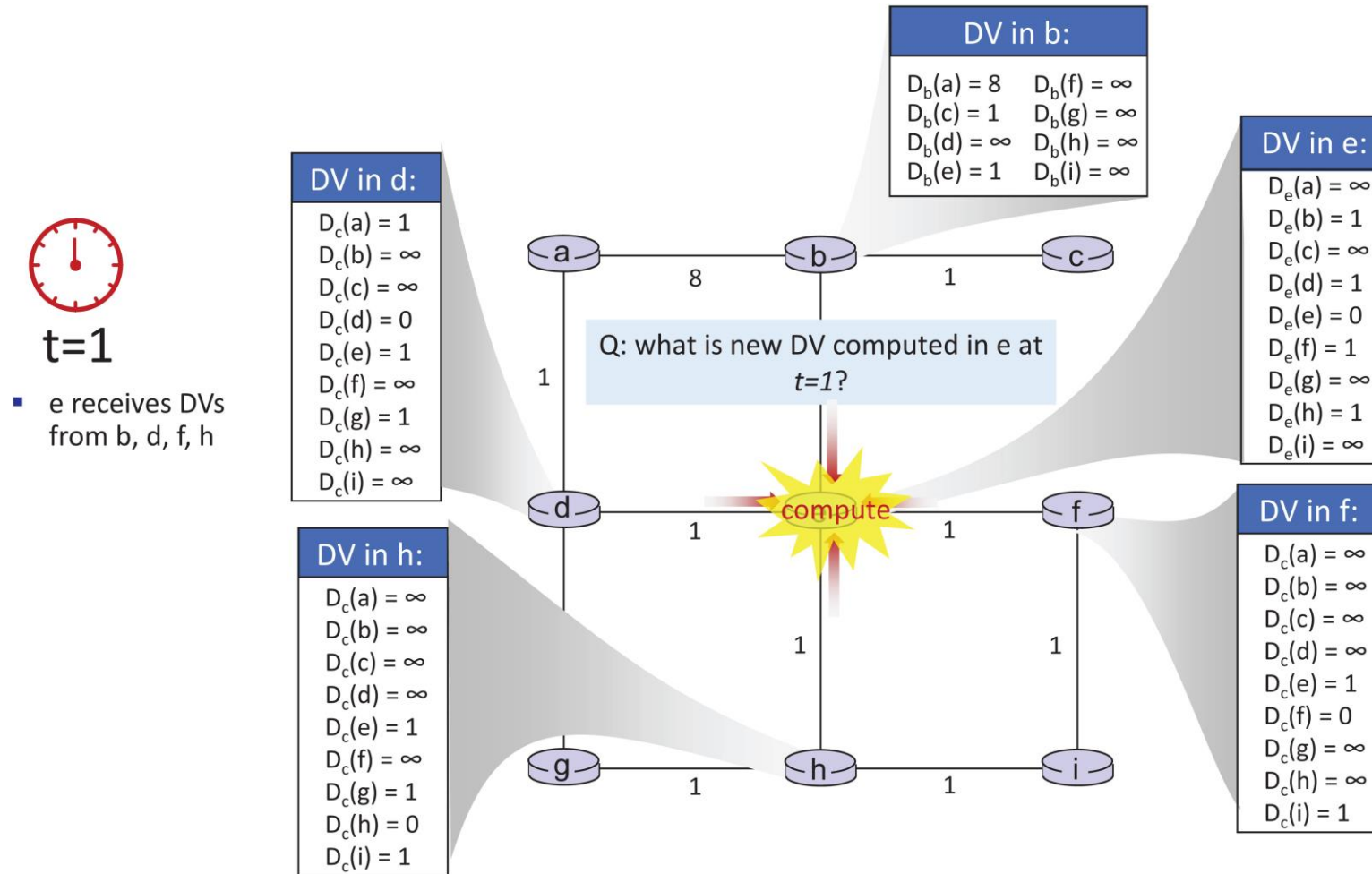
$$\begin{aligned} D_c(a) &= \min\{c_{c,b} + D_b(a)\} = 1 + 8 = 9 \\ D_c(b) &= \min\{c_{c,b} + D_b(b)\} = 1 + 0 = 1 \\ D_c(d) &= \min\{c_{c,b} + D_b(d)\} = 1 + \infty = \infty \\ D_c(e) &= \min\{c_{c,b} + D_b(e)\} = 1 + 1 = 2 \\ D_c(f) &= \min\{c_{c,b} + D_b(f)\} = 1 + \infty = \infty \\ D_c(g) &= \min\{c_{c,b} + D_b(g)\} = 1 + \infty = \infty \\ D_c(h) &= \min\{c_{c,b} + D_b(h)\} = 1 + \infty = \infty \\ D_c(i) &= \min\{c_{c,b} + D_b(i)\} = 1 + \infty = \infty \end{aligned}$$



DV in c:
$D_c(a) = 9$
$D_c(b) = 1$
$D_c(c) = 0$
$D_c(d) = 2$
$D_c(e) = \infty$
$D_c(f) = \infty$
$D_c(g) = \infty$
$D_c(h) = \infty$
$D_c(i) = \infty$

* Check out the online interactive exercises for more examples:
http://gaia.cs.umass.edu/kurose_ross/interactive/

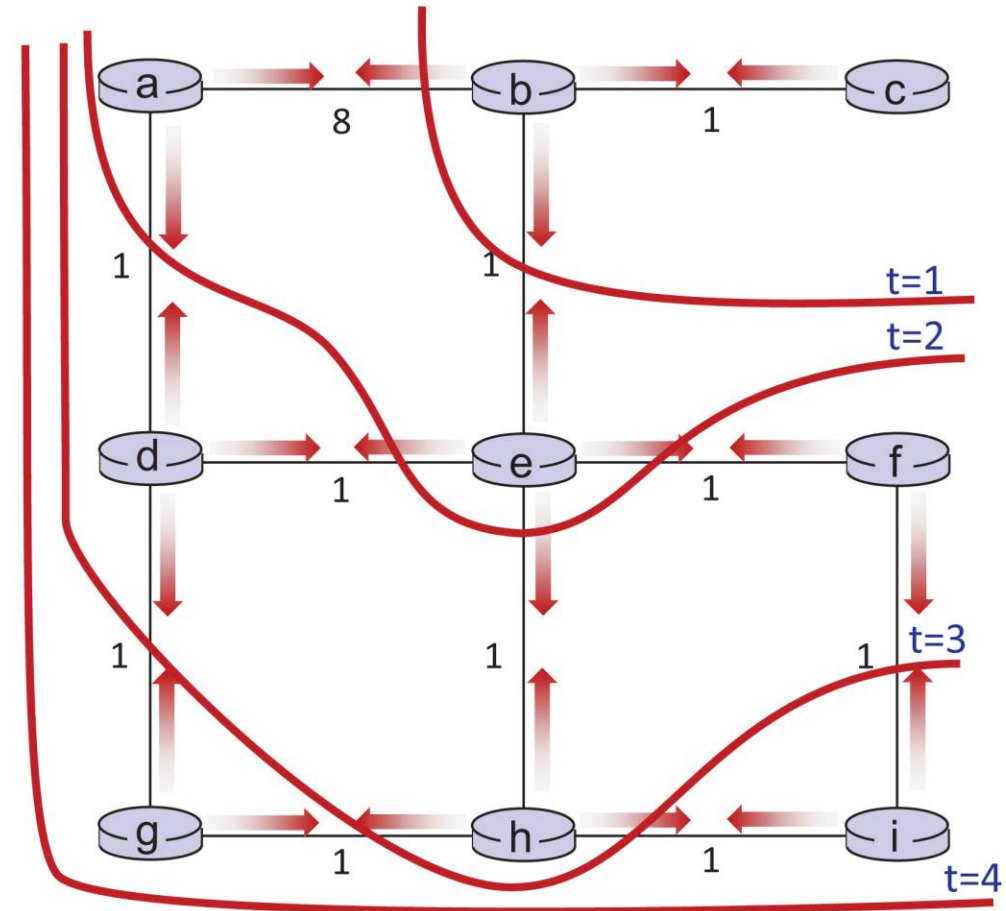
Distance Vector Example: Computation (5 of 5)



Distance Vector: State Information Diffusion

Iterative communication, computation steps diffuses information through network:

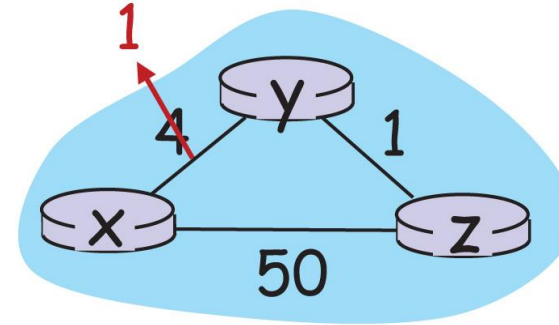
-  $t=0$ c's state at $t=0$ is at c only
-  $t=1$ c's state at $t=0$ has propagated to b, and may influence distance vector computations up to **1** hop away, i.e., at b
-  $t=2$ c's state at $t=0$ may now influence distance vector computations up to **2** hops away, i.e., at b and now at a, e as well
-  $t=3$ c's state at $t=0$ may influence distance vector computations up to **3** hops away, i.e., at d, f, h
-  $t=4$ c's state at $t=0$ may influence distance vector computations up to **4** hops away, i.e., at g, i



Distance Vector: Link Cost Changes (1 of 2)

link cost changes:

- node detects local link cost change
- updates routing info, recalculates local DV
- if DV changes, notify neighbors



t_0 : y detects link-cost change, updates its DV, informs its neighbors.

“good news
travels fast”

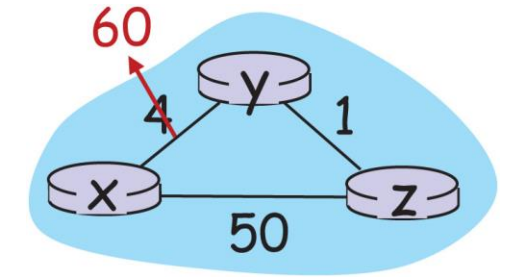
t_1 : z receives update from y, updates its DV, computes new least cost to x, sends its neighbors its DV.

t_2 : y receives z's update, updates its DV. y's least costs do *not* change, so y does **not** send a message to z.

Distance Vector: Link Cost Changes (2 of 2)

link cost changes:

- node detects local link cost change
 - “bad news travels slow” – count-to-infinity problem:
 - y sees direct link to x has new cost 60, but z has said it has a path at cost of 5. So y computes “my new cost to x will be 6, via z); notifies z of new cost of 6 to x.
 - z learns that path to x via y has new cost 6, so z computes “my new cost to x will be 7 via y), notifies y of new cost of 7 to x.
 - y learns that path to x via z has new cost 7, so y computes “my new cost to x will be 8 via y), notifies z of new cost of 8 to x.
 - z learns that path to x via y has new cost 8, so z computes “my new cost to x will be 9 via y), notifies y of new cost of 9 to x.
-
- see text for solutions. **Distributed algorithms are tricky!**



Comparison of LS and DV Algorithms

message complexity

LS: n routers, $O(n^2)$ messages sent

DV: exchange between neighbors;
convergence time varies

speed of convergence

LS: $O(n^2)$ algorithm, $O(n^2)$ messages

- may have oscillations

DV: convergence time varies

- may have routing loops
- count-to-infinity problem

robustness: what happens if router malfunctions, or is compromised?

LS:

- router can advertise incorrect **link** cost
- each router computes only its **own** table

DV:

- DV router can advertise incorrect **path** cost (“I have a **really** low-cost path to everywhere”): **black-holing**
- each router’s DV is used by others: error propagate thru network

Network Layer: “Control Plane” Roadmap (5 of 10)

- introduction
- routing protocols
- intra-ISP routing: OSPF
- routing among ISPs: BGP
- Internet Control Message Protocol

Making Routing Scalable

our routing study thus far – idealized

- all routers identical
- network “flat”

... not true in practice

scale: billions of destinations:

- can't store all destinations in routing tables!
- routing table exchange would swamp links!

administrative autonomy:

- Internet: a network of networks
- each network admin may want to control routing in its own network

Internet Approach to Scalable Routing

aggregate routers into regions known as “autonomous systems” (AS) (a.k.a. “domains”)

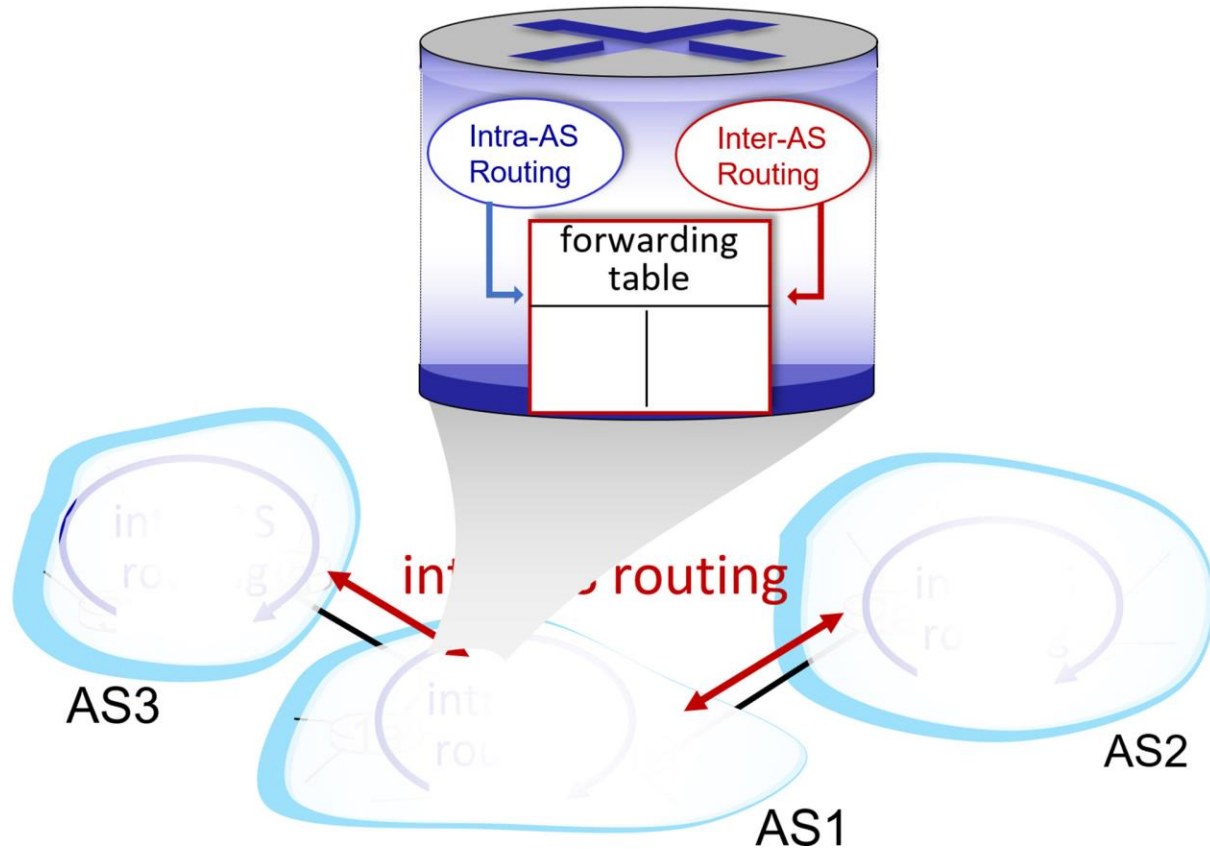
intra-AS (aka “intra-domain”): routing among routers **within same AS** (“**network**”)

- all routers in AS must run same intra-domain protocol
- routers in different AS can run different intra-domain routing protocols
- **gateway router:** at “edge” of its own AS, has link(s) to router(s) in other AS'es

inter-AS (aka “inter-domain”): routing **among** AS'es

- gateways perform inter-domain routing (as well as intra-domain routing)

Interconnected ASes (1 of 2)



forwarding table configured by intra- and inter-AS routing algorithms

- intra-AS routing determine entries for destinations within AS
- inter-AS & intra-AS determine entries for external destinations

Inter-AS Routing: a Role in Intradomain Forwarding

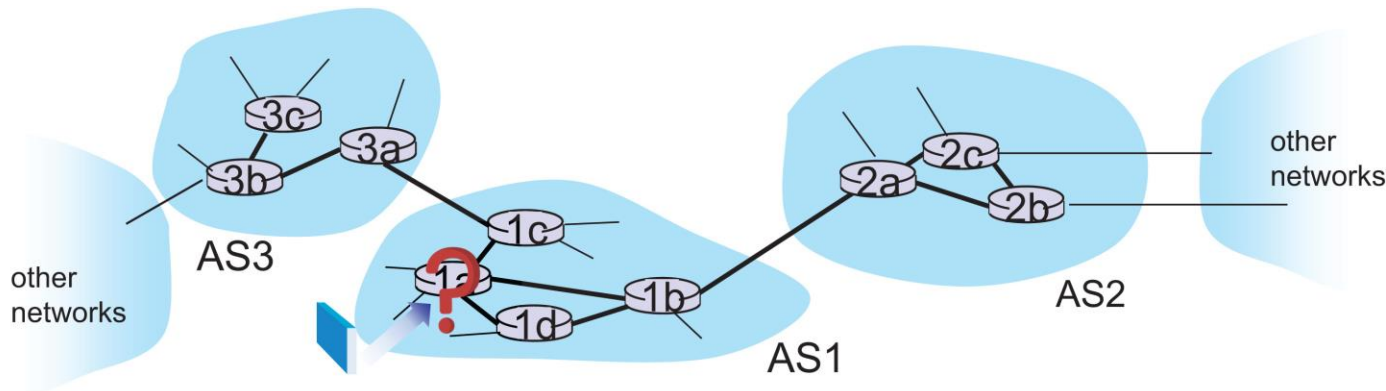
- suppose router in AS1 receives datagram destined outside of AS1:



- router should forward packet to gateway router in AS1, but which one?

AS1 inter-domain routing must:

1. learn which destinations reachable through AS2, which through AS3
2. propagate this reachability info to all routers in AS1



Intra-AS Routing: Routing Within an AS

most common intra-AS routing protocols:

- **RIP: Routing Information Protocol** [RFC 1723]
 - classic DV: DVs exchanged every 30 secs
 - no longer widely used
- **EIGRP: Enhanced Interior Gateway Routing Protocol**
 - DV based
 - formerly Cisco-proprietary for decades (became open in 2013 [RFC 7868])
- **OSPF: Open Shortest Path First** [RFC 2328]
 - link-state routing
 - IS-IS protocol (ISO standard, not RFC standard) essentially same as OSPF

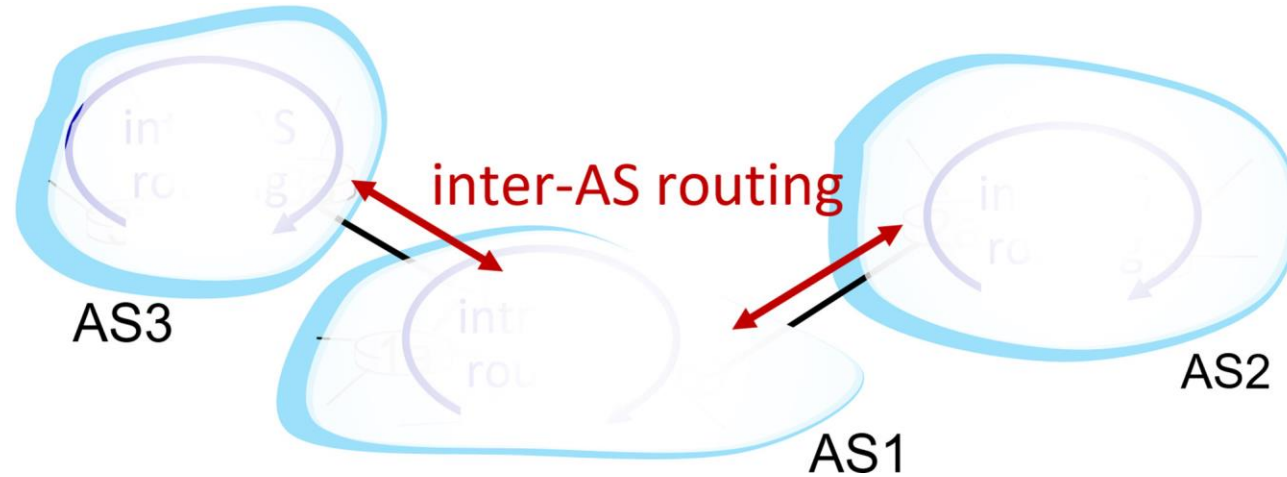
Network Layer: “Control Plane” Roadmap (6 of 10)

- introduction
- routing protocols
- intra-ISP routing: OSPF
- routing among ISPs: BGP
- SDN control plane
- Internet Control Message Protocol



- network management, configuration
 - SNMP
 - NETCONF/YANG

Interconnected ASes (2 of 2)



intra-AS (aka “intra-domain”): routing among routers **within same AS** (“**network**”)

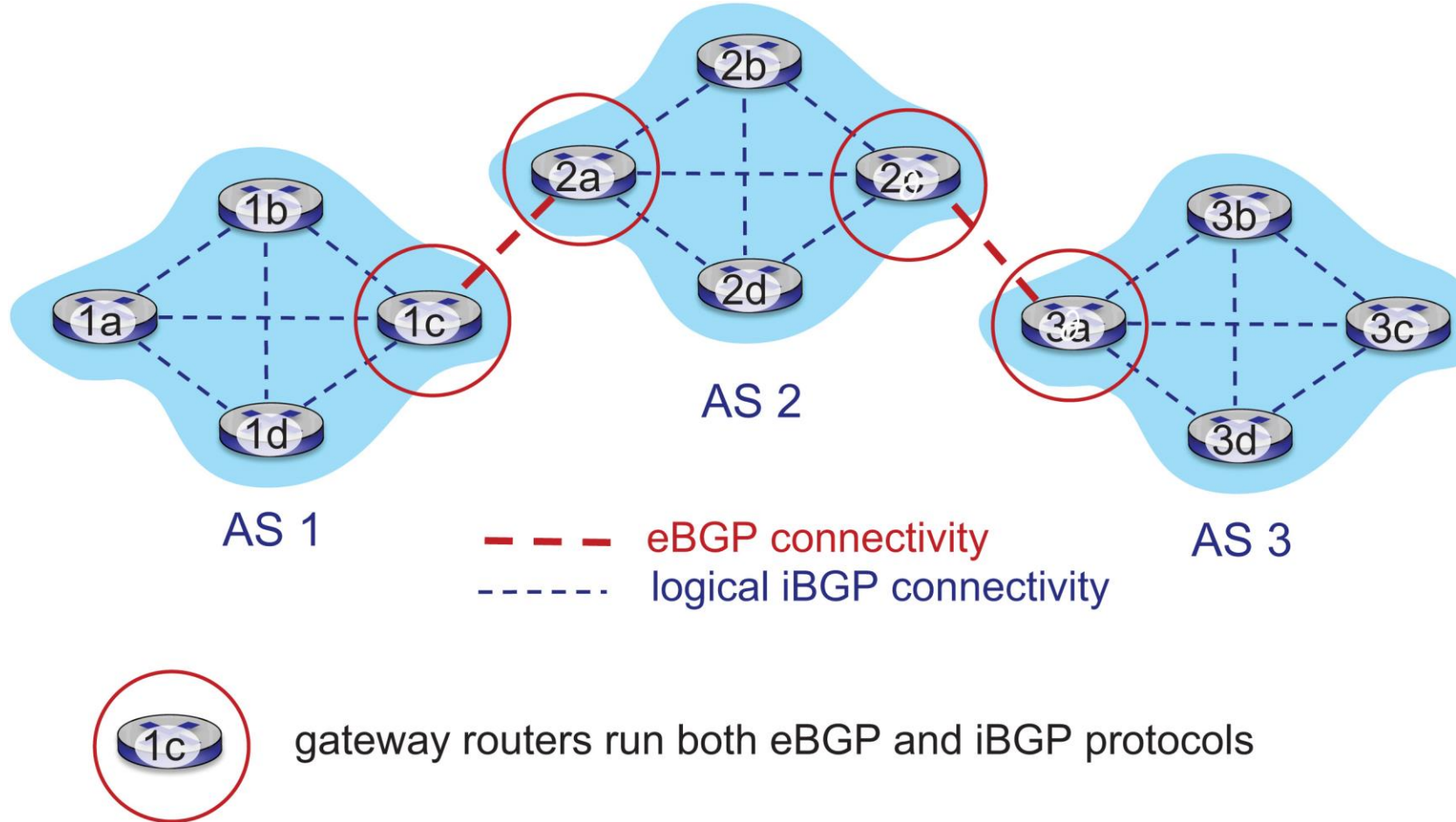


inter-AS (aka “inter-domain”): routing **among** AS'es

Internet Inter-AS Routing: BGP

- BGP (Border Gateway Protocol): **the** de facto inter-domain routing protocol
 - “glue that holds the Internet together”
- allows subnet to advertise its existence, and the destinations it can reach, to rest of Internet: **“I am here, here is who I can reach, and how”**
- BGP provides each AS a means to:
 - obtain destination network reachability info from neighboring ASes (eBGP)
 - determine routes to other networks based on reachability information and **policy**
 - propagate reachability information to all AS-internal routers (iBGP)
 - **advertise** (to neighboring networks) destination reachability info

eBGP, iBGP Connections



Why Different Intra-, Inter-AS Routing ?

policy:

- inter-AS: admin wants control over how its traffic routed, who routes through its network
- intra-AS: single admin, so policy less of an issue

scale:

- hierarchical routing saves table size, reduced update traffic

performance:

- intra-AS: can focus on performance
- inter-AS: policy dominates over performance

Network Layer: “Control Plane” Roadmap (8 of 10)

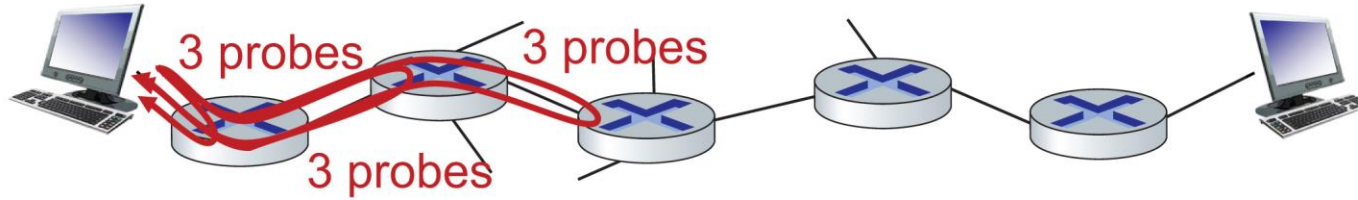
- introduction
- routing protocols
- intra-ISP routing: OSPF
- routing among ISPs: BGP
- Internet Control Message Protocol

ICMP: Internet Control Message Protocol

- used by hosts and routers to communicate network-level information
 - error reporting: unreachable host, network, port, protocol
 - echo request/reply (used by ping)
- network-layer “above” IP:
 - ICMP messages carried in IP datagrams
- **ICMP message:** type, code plus first 8 bytes of IP datagram causing error

Type	Code	Description
0	0	echo reply (ping)
3	0	dest. network unreachable
3	1	dest host unreachable
3	2	dest protocol unreachable
3	3	dest port unreachable
3	6	dest network unknown
3	7	dest host unknown
4	0	source quench (congestion control - not used)
8	0	echo request (ping)
9	0	route advertisement
10	0	router discovery
11	0	TTL expired
12	0	bad IP header

Traceroute and ICMP



- source sends sets of UDP segments to destination
 - 1st set has TTL =1, 2nd set has TTL=2, etc.
- datagram in n th set arrives to n th router:
 - router discards datagram and sends source ICMP message (type 11, code 0)
 - ICMP message possibly includes name of router & IP address
- when ICMP message arrives at source: record RTTs

stopping criteria:

- UDP segment eventually arrives at destination host
- destination returns ICMP “port unreachable” message (type 3, code 3)
- source stops